

# Linear Algebra

## Lecture 09

Vector spaces, Row spaces, Column spaces.

**By Noorullah ibrahimi**

## Objectives

### Vector Spaces

- Understand the concept of vector spaces and their properties.
- Learn vector addition and scalar multiplication.
- Identify subspaces, span, basis, and dimension.

### Row Spaces

- Understand the row space of a matrix.
- Analyze relationships among matrix rows.
- Use row operations to determine rank and linear dependence.

### Column Spaces

- Understand the column space of a matrix.
- Analyze how columns generate vectors through linear combinations.
- Determine whether a system of equations has a solution.

## Outcomes

### Vector Spaces

- Apply vector space properties to solve problems.
- Determine basis, dimension, and span of a vector space.
- Test vectors for linear independence.

### Row Spaces

- Find the row space of a matrix.
- Determine the rank of a matrix.
- Identify dependent and independent equations.

### Column Spaces

- Find the column space of a matrix.
- Determine whether a vector belongs to the column space.
- Analyze the solvability of systems of linear equations.

**Set:** A set is a collection of distinct elements.

### Examples

$\{\text{dog, cat, fish, bird}\}$

Set of animals



A set of flags

$\{1, 2, 3, 4, 5 \dots\}$

Set of numbers

If nothing is inside the set it is an empty set

$$\emptyset = \{ \}$$

A set is denoted by a cursive capital letter

$X, Y, S$

$$X = \{a, b, c\}$$

## A space is just a set with some defined properties

Just like vector sets by itself does not mean anything and we can not do much with it. For example, how do you compute  $\{ \text{🇧🇷} + \text{🇨🇳} \}$

We do not know because it was not previously defined

This is where the concept of space come in

Space is a set where certain structures are defined

For example  $\{ \text{🇧🇷} + \text{🇨🇳} \}$

This could mean the summation of the population of the 2 country

## vector space

**vector space** is just a collection of objects (which we call vectors) where you can do two main things without breaking the rules of the space:

1. **Add** any two vectors together to get a new vector that is still in the space.
2. **Scale** any vector by multiplying it by a number (a scalar) to get a new vector that is still in the space.

## The 8 Rules of the vector space

If a set of objects can't pass all eight of these tests under addition and scalar multiplication, it is not a vector space.

### Vector Addition Rules

These rules ensure that adding vectors together behaves predictably.

- **Commutativity:** The order doesn't matter.

If  $u, v$  are vectors

$$u + v = v + u$$

- **Associativity:** Grouping doesn't matter when adding three or more.

$$(u + v) + w = u + (v + w)$$

- **Identity Element:** There is a unique "zero vector"  $0$  that leaves any vector unchanged.

$$u + 0 = u$$

- **Inverse Element:** Every vector has an exact opposite that pulls it back to zero.

$$u + (-u) = 0$$

## Scalar Multiplication Rules

- **Distributivity over Scalar Addition:** Scaling a vector by two added numbers is the same as scaling it by each separately and adding the results.

$$(c + d)u = cu + du$$

- **Compatibility of Multiplication:** Scaling a vector consecutively works exactly like multiplying the scalars together first.

$$c(du) = (cd)u$$

- **Identity Scalar:** Multiplying any vector by the number 1 leaves it completely unchanged.

$$1u = u$$

## EXAMPLE

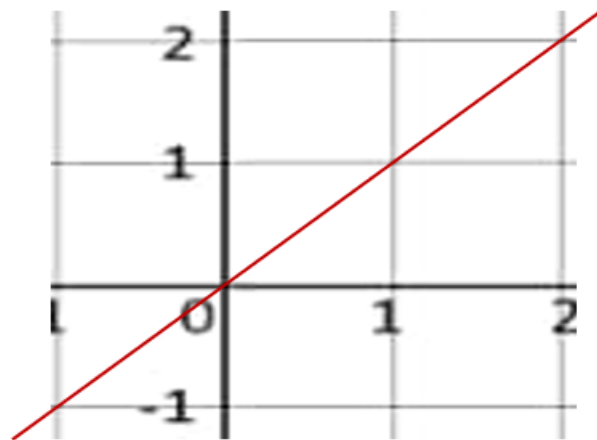
The 2D Plane ( $\mathbf{R}^2$ ): Think of standard x, y coordinates. If you take the arrow  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$  and add it to  $\begin{bmatrix} 3 \\ 1 \end{bmatrix}$ , you get  $\begin{bmatrix} 4 \\ 3 \end{bmatrix}$ , which is still on the flat plane. If you multiply  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$  by 3, you  $\begin{bmatrix} 3 \\ 6 \end{bmatrix}$  still on the plane.

## A set can be defined by a vector

Given the vector  $x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  we can define a space as all possible points reachable by some constant multiplying the vector.

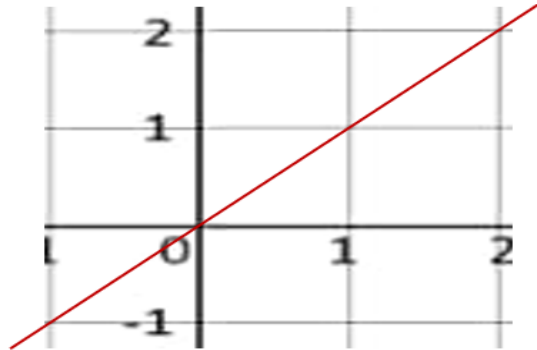
$$v = \alpha \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

for example,  $v = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  or  $v = -2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



Since this set is defined by a vector, so it come with all properties of vector addition subtraction, hence it is a space with defined operations.

You can imagine every point on this line as part of the set.



This set has infinite points on it

This is an example of 2-d space

## linear combination of the vectors

### DEFINITION

If  $w$  is a vector in  $\mathbb{R}^n$ , then  $w$  is said to be a linear combination of the vectors  $v_1, v_2, \dots, v_r$  in  $\mathbb{R}^n$  if it can be expressed in the form

$w = k_1 v_1 + k_2 v_2 + \dots + k_r v_r$  where  $k_1, k_2, \dots, k_r$  are scalars.

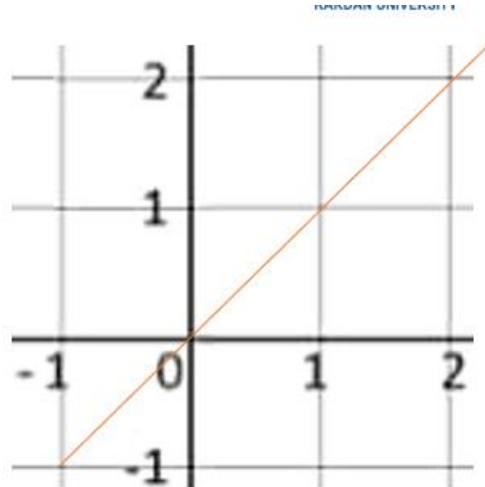
These scalars are called the coefficients of the linear combination.

## Span

This space is the span of vector  $x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

**Span** is very important concept

- This is the set of all possible points reachable by one or multiple scaled vectors



the span of  $x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

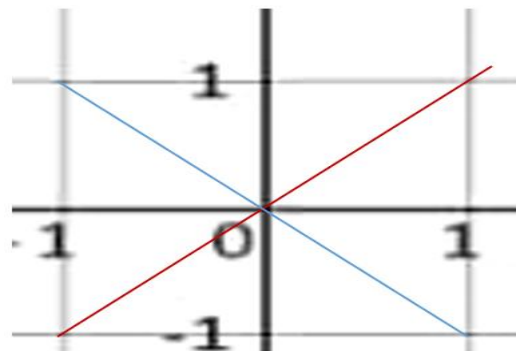
$\begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1.5 \\ 1.5 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 5 \end{bmatrix}, \begin{bmatrix} 100 \\ 100 \end{bmatrix} \dots \dots, \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -0.5 \\ -0.5 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \end{bmatrix}, \begin{bmatrix} -2 \\ -2 \end{bmatrix} \dots \dots \dots$

All these vectors are the same because they are all along the same line.

The red line is the span of  $x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

The blue line is the span of  $x = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

they both intersect at point (0,0)



Span is a very important concept

it is the set all point reachable by one or multiple scaled vectors

## The span of multiple vectors

With a vector  $v$  its span is

$S = \text{span}(v) = \{\alpha v : \alpha \in \mathbb{R}\}$  This notation is called the set builder notation.

It defines a set such that  $\alpha$  can be any real number.

You may sometime see a line instead.

But you can also have multiple vectors

$v_1, v_2, v_3, \dots$ , its span would be

$$S = \text{span}(v_1, v_2, v_3 \dots) = \{(av_1, bv_2 \dots) : a, b \in \mathbb{R}\}$$

For example, you have 2 vectors

$$v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

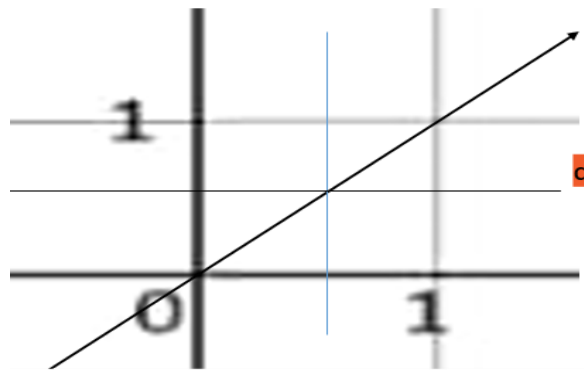
Their span would cover the entire 2D space

For example, the point d is in the span because

$$d = v_1 + \frac{1}{2} v_2$$

The vectors used to create the span of a space are called basis

$$\begin{bmatrix} 1.5 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix}$$



Every single point on this 2D plane can be achieved by some combination of the 2 vectors

## How do you know if a point is in the span for a set of vectors?

By definition if a set of vectors can scale and sum up to a target point, then the target is in the span

Given  $\{v_1, v_2, v_3\}$  and the target vector  $u$

$$u \in \text{span}\{v_1, v_2, v_3\}?$$

This is equivalent to asking if there exists

$a, b, c$  such that

$$av_1 + bv_2 + cv_2 = u$$

## For example

$$a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

This gets harder if we have a lot of vectors

**Matrix multiplication is the same operation**

$$a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{cases} a + b + 2c = 2 \\ b + 2c = 1 \end{cases}$$

$$\begin{cases} a + b + 2c = 2 \\ b + 2c = 1 \end{cases}$$



**Identifying if a point is in the span of a set of vectors is identical**  
to solving a system of linear equations.

If a solution exist (infinite or unique), then the target is in the span

This is why gaussian elimination is so important

**Matric multiplication is the same operation**

$$a \begin{bmatrix} 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c \begin{bmatrix} 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{cases} a + b + 2c = 2 \\ b + 2c = 1 \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{cases} a + b + 2c = 2 \\ b + 2c = 1 \end{cases}$$

**Here, we are interpreting each column as a vector**

**The space span by these columns vectors is called column space**